

A study memo on implicit function theorem and method of Lagrange multiplier

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1 Inverse function theorem

Lemma 1.1. *Let*

$$(S1) \ I_b := (-b, b)^{n+1} \text{ and } J_b := (-b, b)^n.$$

$$(S2) \ a \in I_b.$$

$$(A1) \ f \in C^1(\bar{I}_b, \mathbb{R}).$$

$$(A2) \ f(a) = 0.$$

$$(A3) \ \alpha := \inf_{x \in I_b} \frac{\partial f}{\partial x_1}(x) > 0.$$

then $r \in C^1(J_b, \mathbb{R})$ such that

$$f(r(y), y) = 0 \quad (\forall y \in J_b) \quad (1)$$

Proof. By (A3), for any $y \in J_b$ there exists only one $r(y) \in (-b, b)$ such that $f(r(y), y) = 0$.

Let us fix arbitrary $y \in J_b$ and fix arbitrary $i \in \{2, \dots, n\}$.

For $z \in \mathbb{R}$ such that $|z|$ is sufficient small,

$$\begin{aligned} 0 &= 0 - 0 \\ &= f(r(y + ze_i), y + ze_i) - f(r(y + ze_i), y) \\ &\quad + f(r(y + ze_i), y) - f(r(y), y) \\ &= \int_0^1 \frac{d}{dt} f(r(y + ze_i), y + tze_i) dt \\ &\quad + \int_0^1 \frac{d}{dt} f(r(y) + t(r(y + ze_i) - r(y)), y) dt \\ &= z \int_0^1 \frac{\partial f}{\partial x_i}(r(y + ze_i), y + tze_i) dt \\ &\quad + (r(y + ze_i) - r(y)) \int_0^1 \frac{\partial f}{\partial x_1}(r(y) + t(r(y + ze_i) - r(y)), y) dt \end{aligned} \quad (2)$$

By (2), $(r(y + ze_i) - r(y)) \leq |z| \frac{1}{\alpha} \sup_{\bar{I}_b} |\frac{\partial f}{\partial x_i}|$. So r is continuous on J_b .

By (A1) and (A3), $\int_0^1 \frac{\partial f}{\partial x_1}(r(y) + t(r(y + ze_i) - r(y)), y) dt > 0$. So, by (2),

$$\frac{(r(y + ze_i) - r(y))}{z} = \frac{(\int_0^1 \frac{\partial f}{\partial x_i}(r(y + ze_i), y + tze_i) dt)}{\int_0^1 \frac{\partial f}{\partial x_1}(r(y) + t(r(y + ze_i) - r(y)), y) dt} \quad (3)$$

By (A1) and continuity of r and (3),

$$\lim_{z \rightarrow 0} \frac{(r(y + ze_i) - r(y))}{z} = \frac{\partial f}{\partial x_i}(r(y), y) \frac{\partial f}{\partial x_1}(r(y), y) \quad (4)$$

Consequently $r \in C^1(J_b, \mathbb{R})$. □

Theorem 1.1 (Inverse function theorem). *Let*

- (S1) U is open set in \mathbb{R}^n .
- (S2) $a \in U$.
- (A1) $f \in C^1(U, \mathbb{R}^n)$.
- (A2) $\det(Jf(a)) > 0$ on U .

then there is $V \subset U$ such that V and $f(V)$ are open set and $f : V \rightarrow f(V)$ is injective and $f^{-1} \in C^1(f(V), V)$.

STEP1: case when $n = 1$. It is easy to show. □

STEP2-1: f is locally injective(case when $n > 1$). Let us fix arbitrary $n_0 \in \mathbb{N}$. We assume the above theorem is true if $n \leq n_0$. Let us assume $n = n_0 + 1$. By (A2), for any $i \in \{1, 2, \dots, n\}$ there is $u_i \in \mathbb{R}^n$ such that $Jf(a)u_i = e_i$. By setting for sufficient $b > 0$ $g : (-b, b)^n \ni t \mapsto f(\sigma_{i=1}^n t_i v_i) \in \mathbb{R}^n$, We can assume $a = 0$ and $f(0) = 0$ and $[-c, c]^n \subset U$ for some $c > 0$. and

$$\frac{\partial f^i}{\partial x_i} > 0 \text{ on } I_c := (-c, c)^n \ (\forall i > 0) \quad (5)$$

By (5), clearly f is injective on I_c . □

STEP2-2: f is locally open map(case when $n > 1$). Next, we will show f is open map in I_c for sufficient small $c > 0$. And by Lemma1.1, there is $c' \in (0, c)$ and $r : C^1(J_{c'}, \mathbb{R})$ such that $f_1(r(y), y) = 0$ ($\forall y \in J_{c'}$). Here, $J_{c'} := (-c', c')^{n_0}$. By resetting c to be sufficient smaller, we can assum that $c = c'$.

We set $\tilde{f} = (f_2, \dots, f_n)$. Let us set $g : J_c \ni y \mapsto \tilde{f}(r(y), y) \in \mathbb{R}^{n_0}$. $Jg(0) = \begin{pmatrix} e_2^T \\ e_3^T \\ \dots \\ e_n^T \end{pmatrix} \begin{pmatrix} dr \\ e_1^T \\ \dots \\ e_{n_0}^T \end{pmatrix} = E_{n_0}$. By the assumption in mathematical induction, there is $c'' \in (0, c)$ such that $g(J_{c''})$ is an open set in \mathbb{R}^{n_0} and g is injective on $J_{c''}$. By resetting c to be sufficient smaller, we can assum that $c = c''$.

Let us fix arbitrary connected open interval $(x_1, x_2) \times J \subset I_c$. We set $I := (x_1, x_2)$. We will show $f(I \times J)$ is open set. Let us fix arbitrary point $f(x_0, y_0) \in f(I \times J)$. Because (5), For any $y \in J$, $f(x_1, y) < f(x_0, y) < f(x_2, y)$. Because \bar{J} is compact, by (5), there is d_1 and d_2 such that

$$f_1(x_1, y) \leq d_1 < f_1(x_0, y) < d_2 \leq f_1(x_2, y) \ (\forall y \in J) \quad (6)$$

We set $W := (d_1, d_2) \times g(J)$. Clearly $f(x, y) \in W$. Because g is open map, W is open set. We will show $W \subset f(I \times J)$. Let us fix arbitrary $(u, g(y)) \in I \times W$. Because $f_1(\cdot, y)$ is continuous and (6), by intermediate value theorem, there is $x \in I$ such that $f_1(x, y) = u$. So $f(x, y) = (f_1(x, y), g(y)) = (u, g(y))$. This means $W \subset f(I \times J)$. Consequently, f is open map in I_c .

We replace f by $f|_{I_c}$. □

STEP2-3: For each i , $\frac{\partial f^{-1}}{\partial w_i}$ exists (case when $n > 1$). Let us fix arbitrary $(u_0, v_0) \in W$. Let us set $(x, y) := f^{-1}(u_0, v_0)$. By using an approach is same with one in STEP2-1, it is enough to show that for any i $\frac{\partial f^{-1}}{\partial w_i}(x_0, y_0)$ exists we can assume that $Jf(x_0, y_0) = E_n$.

Let us fix arbitrary $i \in \{1, 2, \dots, n\}$. Let us pick up $j \in (\{1, 2, \dots, n\} \setminus \{i\})$. By swaping x_j by x_1 and swaping f_j by f_1 , we can assume $j = 1$. By using an approach is same with one in STEP2-2, there is $R \in C^1(J_c, \mathbb{R})$ such that

$$f_1(R(y), y) = u \quad (\forall y \in J_c) \quad (7)$$

and $G : J_c \ni y \mapsto \tilde{f}(R(y), y) \in G(J_c)$ is injective and open map and class C^1 and G^{-1} is class C^1 .

For any t such that $|t|$ is sufficient small,

$$f^{-1}((u, v) + te_i) = (R(G^{-1}((u, v) + te_i)), G^{-1}((u, v) + te_i)) \quad (8)$$

The right side of (8) is differentiable at $t = 0$.

$\frac{\partial f^{-1}}{\partial w_i}(x_0, y_0)$ exists. \square

STEP2-4 f^{-1} is class C^1 (case when $n > 1$). Lastly, we will show $f^{-1} \in C^1(W, I_c)$.

By STEP2-3,

$$ff^{-1}(w) = w \quad (\forall w \in W) \quad (9)$$

So,

$$\frac{\partial f^{-1}}{\partial w_i}(w) = Jf(f^{-1}(w))^{-1}e_i \quad (\forall i, \forall w \in W) \quad (10)$$

The right side of (10) is continuous with respect to w . So f^{-1} is class C^1 . \square

Remark 1.1. *There is a map which does not have global inverse map and has nonsingular Jacobi matrix at every point. $f : (0, \infty) \times \mathbb{R} \ni (r, \theta) \mapsto r \begin{pmatrix} r \cos(\theta) \\ r \sin(\theta) \end{pmatrix} \in \mathbb{R}^2 \setminus \{0\}$ is a example of such maps.*

Remark 1.2. *[1] gives a sufficient condition for existence of global inverse map.*

The following proposition is easily proved by inverse mapping theorem.

Corollary 1.1. (S1) U is open set in \mathbb{R}^n .

(S2) $a \in U$.

(A1) $f \in C^1(U, \mathbb{R}^n)$.

(S3) V is open set in \mathbb{R}^n such that $f(U) \subset V$.

(A2) $g \in C^1(V, \mathbb{R}^n)$.

(A3) $g \circ f = id_U$.

then there is $f(U)$ is open set.

2 Implicit function theorem

Theorem 2.1 (Implicit function theorem). *Let*

(S1) U is open set in \mathbb{R}^{m+n} .

(S2) $a := (a_1, a_2, \dots, a_m)$ and $b := (b_1, b_2, \dots, b_n)$ and $c := (a, b)$.

(S3) $c \in U$.

(A1) $f \in C^1(U, \mathbb{R}^m)$.

(A2) $f(c) = 0$.

(A3) $\det\left\{\frac{\partial f_i}{\partial x_j}(a)\right\}_{1 \leq i, j \leq m} \neq 0$.

then there is an open subset in \mathbb{R}^n V and $r \in C^1(V, \mathbb{R}^m)$ such that $b \in V$ and $r(b) = a$ and

$$(r(y), y) \subset U \text{ and } f(r(y), y) = 0 \quad (\forall y \in V) \quad (11)$$

Proof. By resetting Bf for $B = \left\{\frac{\partial f_i}{\partial x_j}(a)\right\}_{1 \leq i, j \leq m}^{-1}$, we can assume.

Let us set $g : U \ni (x, y) \mapsto (f(x), y) \in \mathbb{R}^{m+n}$. Because $\det(Jg(c)) \neq 0$, by inverse function theorem, there is an open neighborhood of c $U' := B(a, \epsilon) \times B(b, \epsilon) \subset U$ such that $g(U')$ is open subset and $g : U' \rightarrow g(U')$ is class C^1 homeomorphisim.

We set $r : B(b, \epsilon) \ni g^{-1}(0, y) \in U'$. Clearly r satisfies the conditions in the above theorem. \square

3 Method of Lagrange multiplier

Theorem 3.1 (Method of Lagrange multiplier). *Let*

(S1) U is open set in \mathbb{R}^{m+n} .

(S2) $a := (a_1, a_2, \dots, a_m)$ and $b := (b_1, b_2, \dots, b_n)$ and $c := (a, b)$.

(S3) $c \in U$.

(S4) $g \in C^1(U, \mathbb{R})$.

(A1) $f \in C^1(U, \mathbb{R}^m)$.

(A2) $f(c) = 0$.

(A3) $\text{rank}(Jf(c)) = m$.

(A4) a is a maximum point of g in U .

then there is $\lambda \in \mathbb{R}^m$ such that

$$dg(a) = \sum_{i=1}^m \lambda_i df_i(a) \quad (12)$$

Proof. By swapping variables, we can assume (A3) in Theorem2.1. We pick r in Theorem2.1. We define (s_1, s_2, \dots, s_n) by $(s_1, s_2, \dots, s_n) := \begin{pmatrix} Jr(b) \\ E_n \end{pmatrix}$ Clearly $\dim \langle s_1, s_2, \dots, s_n \rangle = n$. So $\dim \langle s_1, s_2, \dots, s_n \rangle^\perp = m$ Because $f(r(\cdot), \cdot) \equiv 0$ in U , $\langle df_1, df_2, \dots, df_m \rangle \subset \langle s_1, s_2, \dots, s_n \rangle^\perp$. By (A3), $\langle df_1, df_2, \dots, df_m \rangle = \langle s_1, s_2, \dots, s_n \rangle^\perp$. Because $g(r(\cdot), \cdot)$ achieves maximum at b , $dg \in \langle s_1, s_2, \dots, s_n \rangle^\perp$. Consequently, there is $\lambda \in \mathbb{R}^m$ such that

$$dg(a) = \sum_{i=1}^m \lambda_i df_i(a) \tag{13}$$

□

References

- [1] D. Gale, H. Nikaido, The Jacobian matrix and global univalence of mappings, Math. Annalen 159, 81-93(1965).